

(See <https://cs.stanford.edu/~knuth/programs.html> for date.)

1. Intro. This is a transcription of my “random matroid” program in #P72.

Standard input contains a sequence of integers. The first of these is the universe size, n , which should be at most 16. Then comes, for $r = 1, 2, \dots$, a list of sets that are stipulated to have rank $\leq r$. Sets are specified in hexadecimal notation, and each list is terminated by 0. Thus, the π -based example in my paper corresponds to the standard input

10 1a 222 64 128 288 10c

because #1a = $2^4 + 2^3 + 2^1$ represents the set $\{1, 3, 4\}$, and #222 represents $\{1, 5, 9\}$, etc. The program appends zeros to the data on standard input if necessary, so trailing zeros can be omitted. Similarly, the standard input

5 7 0 1e

specifies a five-point matroid in which $\{0, 1, 2\}$ has rank ≤ 2 and $\{1, 2, 3, 4\}$ has rank ≤ 3 .

```
#define nmax 16 /* to go higher, extend print_set to larger-than-hex digits */
#define lmax 25742 /* 2((16/8) + 1), a safe upper bound on list size */
#include <stdio.h>
int n; /* number of elements in the universe */
int mask; /* 2n - 1 */
int S[lmax + 1], L[lmax + 1]; /* list memory */
int r; /* the current rank */
int h; /* head of circular list of closed sets for rank r */
int nh; /* head of circular list being formed for rank r + 1 */
int avail; /* beginning the list of available space */
int unused; /* the first unused slot in S and L arrays */
int x; /* a set used to communicate with the insert routine */
int rank[1 << nmax]; /* 100 + cardinality, or assigned rank */
<Subroutines 8>
main()
{
    register int i, j, k;
    if (scanf("%d", &n) != 1 || n > 16 || n < 0) {
        fprintf(stderr, "Sorry, I can't deal with a universe of size %d.\n", n);
        exit(-1);
    }
    mask = (1 << n) - 1;
    <Set initial contents of rank table 2>;
    <Initialize list memory to available 3>;
    rank[0] = 0, r = 0;
    while (rank[mask] > r) <Pass from rank r to r + 1 4>;
    print_circuits();
}
```

```
2. <Set initial contents of rank table 2> ≡
k = 1;
rank[0] = 100;
while (k ≤ mask) {
    for (i = 0; i < k; i++) rank[k + i] = rank[i] + 1;
    k = k + k;
}
```

This code is used in section 1.

3. The published paper had a comparatively inefficient algorithm here; it initialized thousands of links that usually remained unused.

```

⟨ Initialize list memory to available 3 ⟩ ≡
  L[1] = 2;
  L[2] = 1;
  S[2] = 0;
  h = 1; /* list containing the empty set */
  unused = 3;

```

This code is used in section 1.

```

4. ⟨ Pass from rank  $r$  to  $r + 1$  4 ⟩ ≡
  {
    ⟨ Create empty list 5 ⟩;
    generate();
    if ( $r$ ) enlarge();
    ⟨ Return list  $h$  to available storage 6 ⟩;
    r++;
    h = nh;
    sort(); /* optional */
    print_list(h);
    ⟨ Assign rank to sets and print independent ones 7 ⟩;
  }

```

This code is used in section 1.

```

5. ⟨ Create empty list 5 ⟩ ≡
  nh = avail;
  if (nh) avail = L[nh];
  else nh = unused++;
  L[nh] = nh;

```

This code is used in section 4.

```

6. ⟨ Return list  $h$  to available storage 6 ⟩ ≡
  for ( $j = h$ ;  $L[j] \neq h$ ;  $j = L[j]$ ) ;
  L[j] = avail;
  avail = h;

```

This code is used in section 4.

```

7. ⟨ Assign rank to sets and print independent ones 7 ⟩ ≡
  printf("Independent sets for rank %d:", r);
  for ( $j = L[h]$ ;  $j \neq h$ ;  $j = L[j]$ ) mark(S[j]);
  printf("\n");

```

This code is used in section 4.

8. The *generate* procedure inserts minimal closed sets for rank $r + 1$ into a circular list headed by nh . (It corresponds to “Step 2” in the published algorithm.)

```

⟨Subroutines 8⟩ ≡
  void insert(void);    /* details coming soon */
  void generate(void)
  {
    register int t, v, y, j, k;
    for (j = L[h]; j ≠ h; j = L[j]) {
      y = S[j];    /* a closed set of rank r */
      t = mask - y;
      ⟨Find all sets in list nh that already contain y and remove excess elements from t 9⟩;
      ⟨Insert y ∪ a for each a ∈ t 10⟩;
    }
  }

```

See also sections 11, 12, 13, 14, 15, 16, 17, and 18.

This code is used in section 1.

```

9. ⟨Find all sets in list nh that already contain y and remove excess elements from t 9⟩ ≡
  for (k = L[nh]; k ≠ nh; k = L[k])
    if ((S[k] & y) ≡ y) t &= ~S[k];

```

This code is used in section 8.

```

10. ⟨Insert y ∪ a for each a ∈ t 10⟩ ≡
  while (t) {
    x = y | (t & -t);
    insert();    /* insert x into nh, possibly enlarging x */
    t &= ~x;
  }

```

This code is used in section 8.

11. The following key procedure basically inserts the set x into list nh . But it augments x if necessary (and deletes existing entries of the list) so that no two entries have an intersection of rank greater than r . Thus it incorporates the idea of “Step 4,” but it is more efficient than a brute force implementation of that step.

```

⟨Subroutines 8⟩ +=
void insert(void)
{
    register int  $j, k$ ;
     $j = nh$ ;
    store:  $S[nh] = x$ ;
    loop:  $k = j$ ;
    contin:  $j = L[k]$ ;
    if ( $rank[S[j] \& x] \leq r$ ) goto loop;
    if ( $j \neq nh$ ) {
        if ( $x \equiv (x | S[j])$ ) { /* remove from list and continue */
             $L[k] = L[j], L[j] = avail, avail = j$ ;
            goto contin;
        } else { /* augment  $x$  and go around again */
             $x |= S[j], nh = j$ ;
            goto store;
        }
    }
     $j = avail$ ;
    if ( $j$ )  $avail = L[j]$ ;
    else  $j = unused++$ ;
     $L[j] = L[nh]$ ;
     $L[nh] = j$ ;
     $S[j] = x$ ;
}

```

12. The *enlarge* procedure inserts sets that are read from standard input until encountering an empty set. (It corresponds to “Step 3.”)

```

⟨Subroutines 8⟩ +=
void enlarge(void)
{
    while (1) {
         $x = 0$ ;
        scanf ("%x", & $x$ );
        if ( $\neg x$ ) return;
        if ( $rank[x] > r$ ) insert();
    }
}

```

13. We don't output a set as a hexadecimal number according to the convention used on standard input; instead, we print an increasing sequence of hexadecimal digits that name the actual set elements. For example, the set that was input as `1a` would be output as `134`.

⟨Subroutines 8⟩ +≡

```
void print_set(int t)
{
    register int j, k;
    printf("_");
    for (j = 1, k = 0; j ≤ t; j ≪= 1, k++)
        if (t & j) printf("%x", k);
}
```

14. ⟨Subroutines 8⟩ +≡

```
void print_list(int h)
{
    register int j;
    printf("Closed sets for rank %d:", r);
    for (j = L[h]; j ≠ h; j = L[j]) print_set(S[j]);
    printf("\n");
}
```

15. The subroutine `mark(m)` sets $rank[m'] = r$ for all subsets $m' \subseteq m$ whose rank is not already $\leq r$, and outputs m' if it is independent (that is, if its rank equals its cardinality).

⟨Subroutines 8⟩ +≡

```
void mark(int m)
{
    register int t, v;
    if (rank[m] > r) {
        if (rank[m] ≡ 100 + r) print_set(m);
        rank[m] = r;
        for (t = m; t; t = v) {
            v = t & (t - 1);
            mark(m - t + v);
        }
    }
}
```

16. I've added a *tl* array to the data structure, to speed up and shorten this routine.

```

⟨Subroutines 8⟩ +=
void sort()
{
    register int i, j, k;
    int hd[101 + nmax], tl[101 + nmax];
    for (i = 100; i ≤ 100 + n; i++) hd[i] = -1;
    j = L[h];
    L[h] = h;
    while (j ≠ h) {
        i = rank[S[j]];
        k = L[j];
        L[j] = hd[i];
        if (L[j] < 0) tl[i] = j;
        hd[i] = j;
        j = k;
    }
    for (i = 100; i ≤ 100 + n; i++)
        if (hd[i] ≥ 0) L[tl[i]] = L[h], L[h] = hd[i];
}

```

17. The parameter *card* is 100 plus the cardinality of *m* in the following subroutine.

```

⟨Subroutines 8⟩ +=
void unmark(int m, int card)
{
    register t, v;
    if (rank[m] < 100) {
        rank[m] = card;
        for (t = mask - m; t; t = v) {
            v = t & (t - 1);
            unmark(m + t - v, card + 1);
        }
    }
}

```

```

18. ⟨Subroutines 8⟩ +=
void print_circuits(void)
{
    register int i, k;
    printf("The_circuits_are:");
    for (k = 1; k ≤ mask; k += k)
        for (i = 0; i < k; i++)
            if (rank[k + i] ≡ rank[i]) {
                print_set(k + i);
                unmark(k + i, rank[i] + 101);
            }
    printf("\n");
}

```

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